

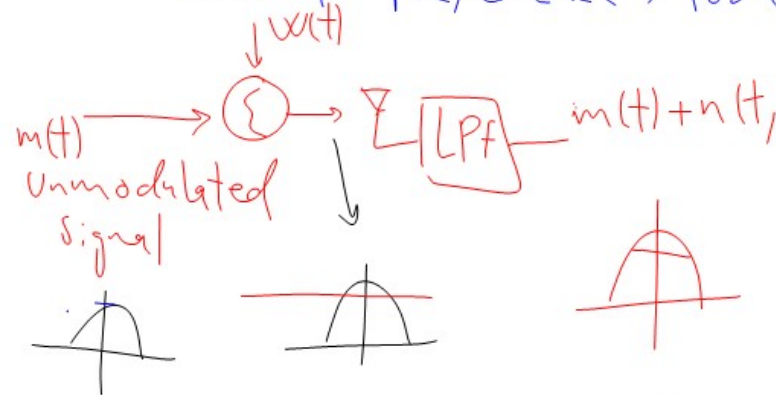
$s(t) + n(t)$: SNR measured at the input of demodulator "pre-detection SNR"

→ it measures the quality of the transmission link and receiver frontend

② $m(t) + n(t)$: SNR measured at the output of the receiver "post-detection SNR"

→ it measures the quality of the demodulation process and the quality of the info received.

To Compare different modulation schemes, we introduce the idea of "Reference Model"



⇒ This model is equivalent to transmitting at baseband.

We made two assumptions:

① The msg power is the same as the modulated $s(t)$ signal power

② The baseband LPF passes the msg signal and rejects out of band noise

We may define "Reference SNR"

$$\begin{aligned} \text{SNR}_{\text{ref}} &= \frac{\text{avg power of the modulated signal}}{\text{avg power of the noise measured within BW of } m(t)} \\ &= \frac{|s(t)|^2}{|n(t)|^2} \end{aligned}$$

We may define "Figure of merit"
to compare diff mod-dem
schemes

$$F = \frac{\text{Post-detection SNR}}{\text{Reference SNR}}$$

The higher figure of merit the
better the system is.

Communications and Signals Processing

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Chapter 9- Outlines

- 9.1 Noise in Communication Systems
- 9.2 Signal-to-Noise Ratios
- 9.3 Band-Pass Receiver Structures
- 9.4 Noise in Linear Receivers Using Coherent Detection
- 9.5 Noise in AM Receivers Using Envelope Detection
- 9.6 Noise in SSB Receivers
- 9.7 Detection of Frequency Modulation (FM)
- 9.8 FM Pre-emphasis and De-emphasis
- 9.9 Summary and Discussion

9.1: Noise in Communication Systems

Written Notes delivered to the student.

Section 9.2: Signal-To-Noise Ratios

9.2: Signal-To-Noise Ratios

Part of it is written notes delivered to the student.

9.2: Signal-To-Noise Ratios

In order to compare different *analog modulation–demodulation schemes*, we introduce the idea of a *reference transmission model* as depicted in Fig.

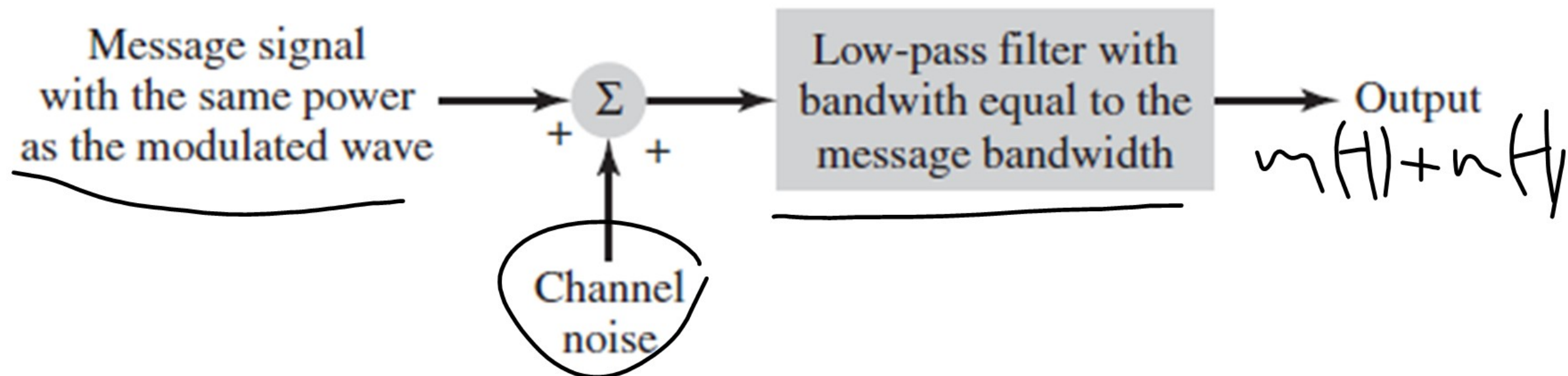


FIGURE 9.4 Reference transmission model for analog communications.

- ❖ This reference model is equivalent to transmitting the message at *baseband*

9.2: Signal-To-Noise Ratios

In this model, two assumptions are made:

1. The message **power** is the same as the modulated signal power of the modulation scheme under study.
2. The baseband low-pass filter passes the message signal and rejects out-of-band noise.

Accordingly, we may define the reference signal-to-noise ratio, SNR_{ref} as

$$SNR_{ref} = \frac{\text{average power of the modulated message signal}}{\text{average power of noise measured in the message bandwidth}} \quad (9.11)$$

9.2: Signal-To-Noise Ratios

- The reference signal-to-noise ratio of Eq. (9.11) may be used to compare different modulation–demodulation schemes by using it *to normalize* the post-detection signal-to-noise ratios
- That is, we may define a *figure of merit* for a particular modulation–demodulation scheme as follows:

$$\text{Figure of merit} = \frac{\text{post-detection SNR}}{\text{reference SNR}}$$

9.2: Signal-To-Noise Ratios

$$\text{Figure of merit} = \frac{\text{post-detection SNR}}{\text{reference SNR}}$$

- Clearly, the *higher* the value that the figure of merit has, the *better* the noise performance of the receiver will be.

9.2: Signal-To-Noise Ratios

To summarize our consideration of signal-to-noise ratios:

- The *pre-detection* SNR is measured before the signal is demodulated.
- The *post-detection* SNR is measured after the signal is demodulated.
- The *reference SNR* is defined on the basis of a baseband transmission model.
- The *figure of merit* is a dimensionless metric for comparing different analog modulation–demodulation schemes and is defined as the ratio of the post-detection and reference SNRs.

Section 9.3: Band-Pass Receiver Structures

9.3: Band-Pass Receiver Structures

- The transmitter includes a modulator that produces an output at a standard *intermediate frequency (IF)* and a local mixer-translates (up-converts) this output to a “channel” or *radio frequency (RF)*.

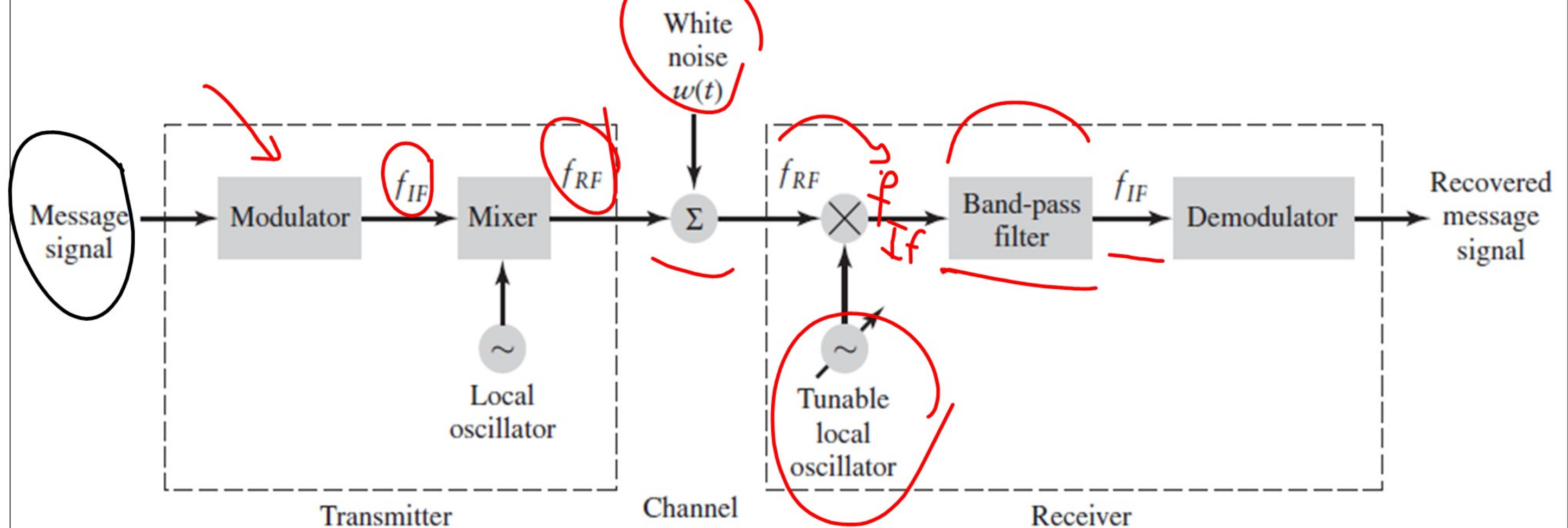


FIGURE 9.5 Block diagram of band-pass transmission showing a superheterodyne receiver.

9.3: Band-Pass Receiver Structures

- The right-hand side of Fig. 9.5 shows an example of a super-heterodyne receiver that was discussed

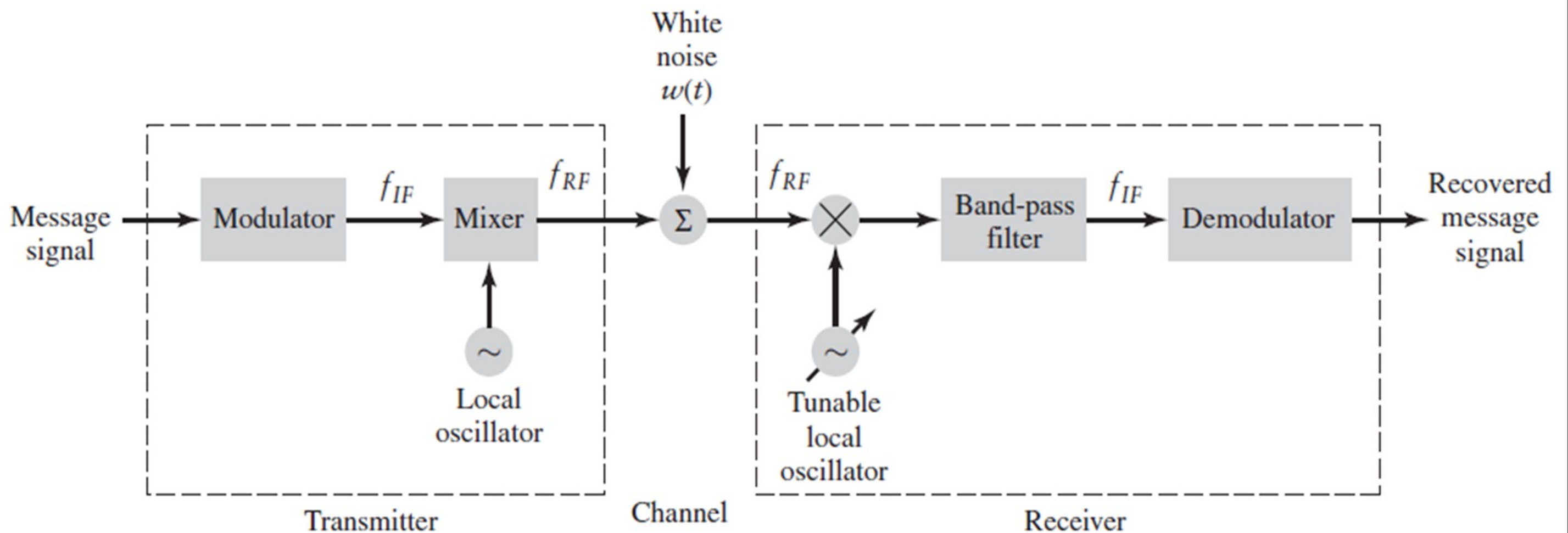


FIGURE 9.5 Block diagram of band-pass transmission showing a superheterodyne receiver.

9.3: Band-Pass Receiver Structures

- At the receiver, a tunable local oscillator frequency-translates (*down-converts*) this *channel frequency (RF)* to a standard *intermediate frequency (IF)* for demodulation

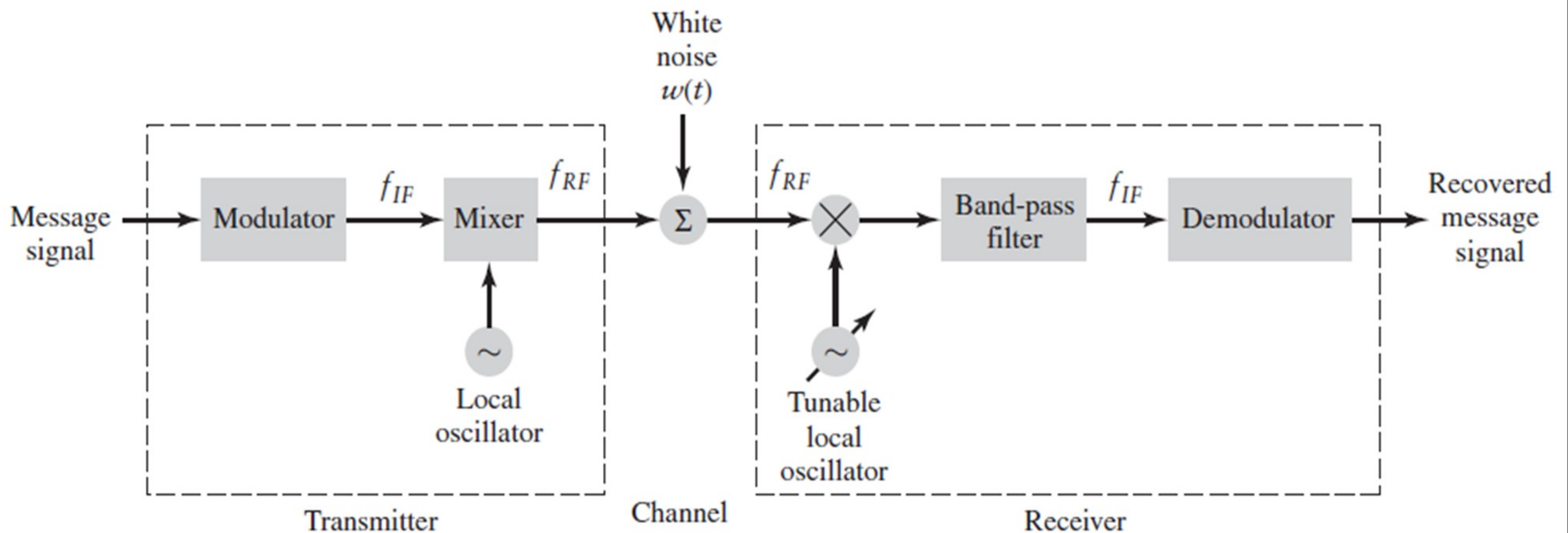
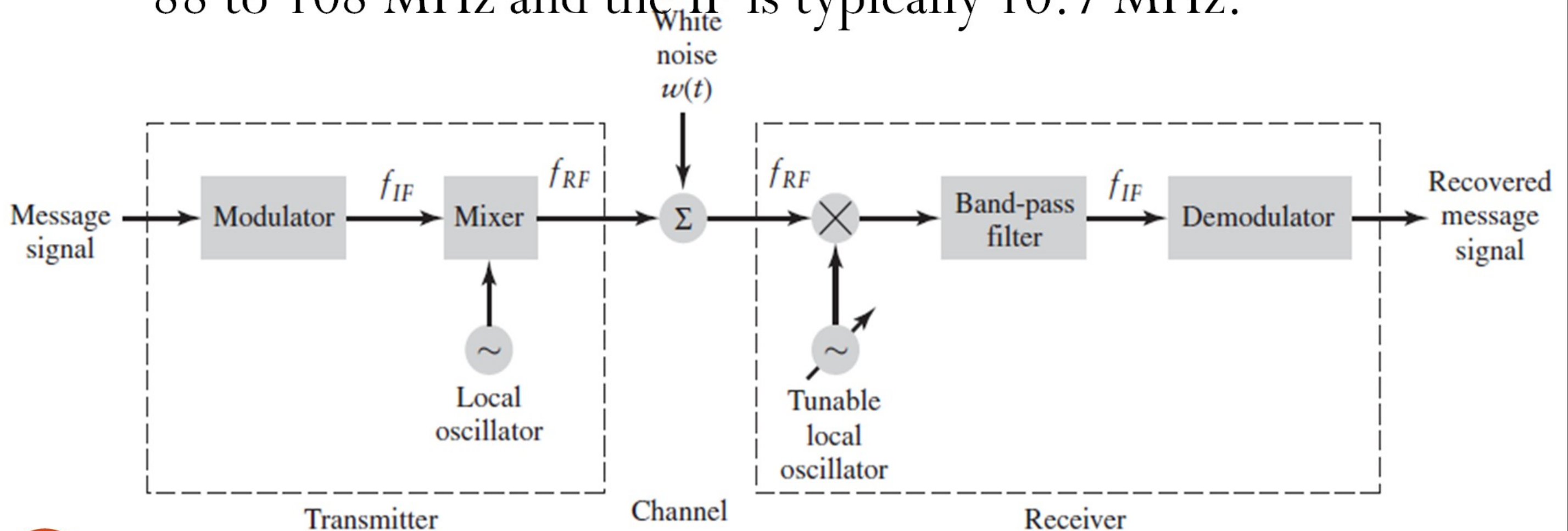


FIGURE 9.5 Block diagram of band-pass transmission showing a superheterodyne receiver.

9.3: Band-Pass Receiver Structures

- Common *examples* are AM radio transmissions, where the RF channels' frequencies lie in the range between 510 and 1600 kHz, and a common IF is 455 kHz; another example is FM radio, where the RF channels are in the range from 88 to 108 MHz and the IF is typically 10.7 MHz.



9.3: Band-Pass Receiver Structures

- Band-pass signals using the in-phase and quadrature representation with

$$s(t) = s_I(t) \cos(2\pi f_c t) - s_Q(t) \sin(2\pi f_c t)$$

where $s_I(t)$ is the in-phase component and $s_Q(t)$ is its quadrature component

9.3: Band-Pass Receiver Structures

- Most receivers immediately limit the white noise power by processing the received signal with a band-pass filter
- Typically, there is a band-pass filter before and after the local oscillator

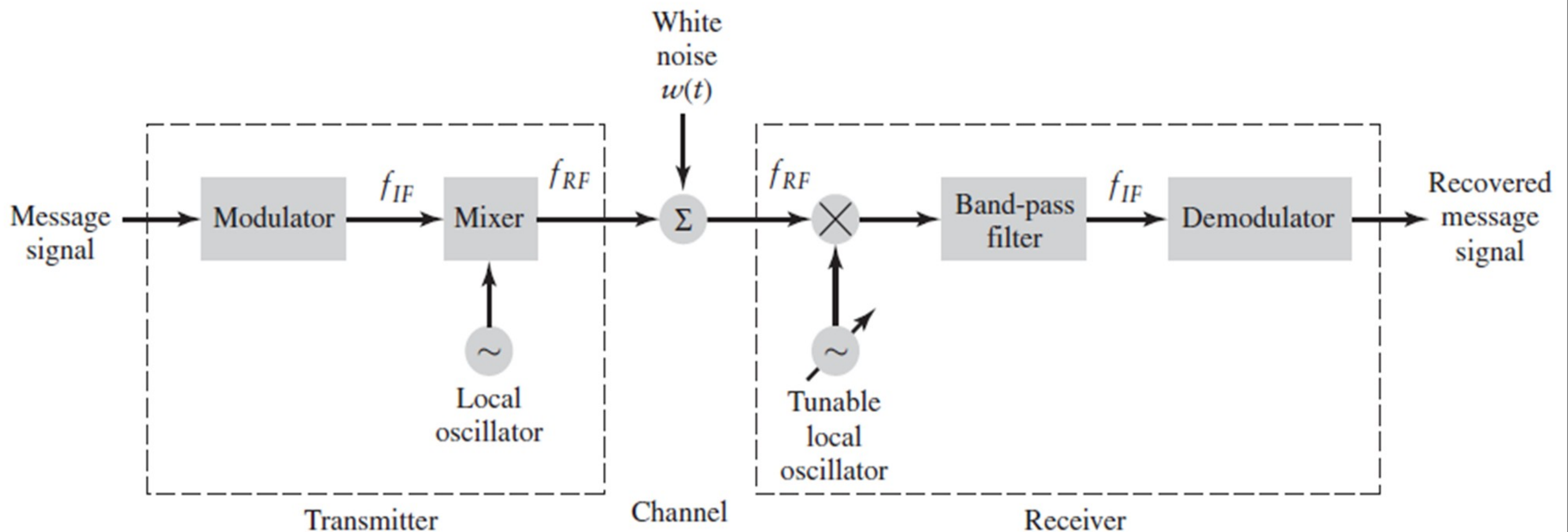
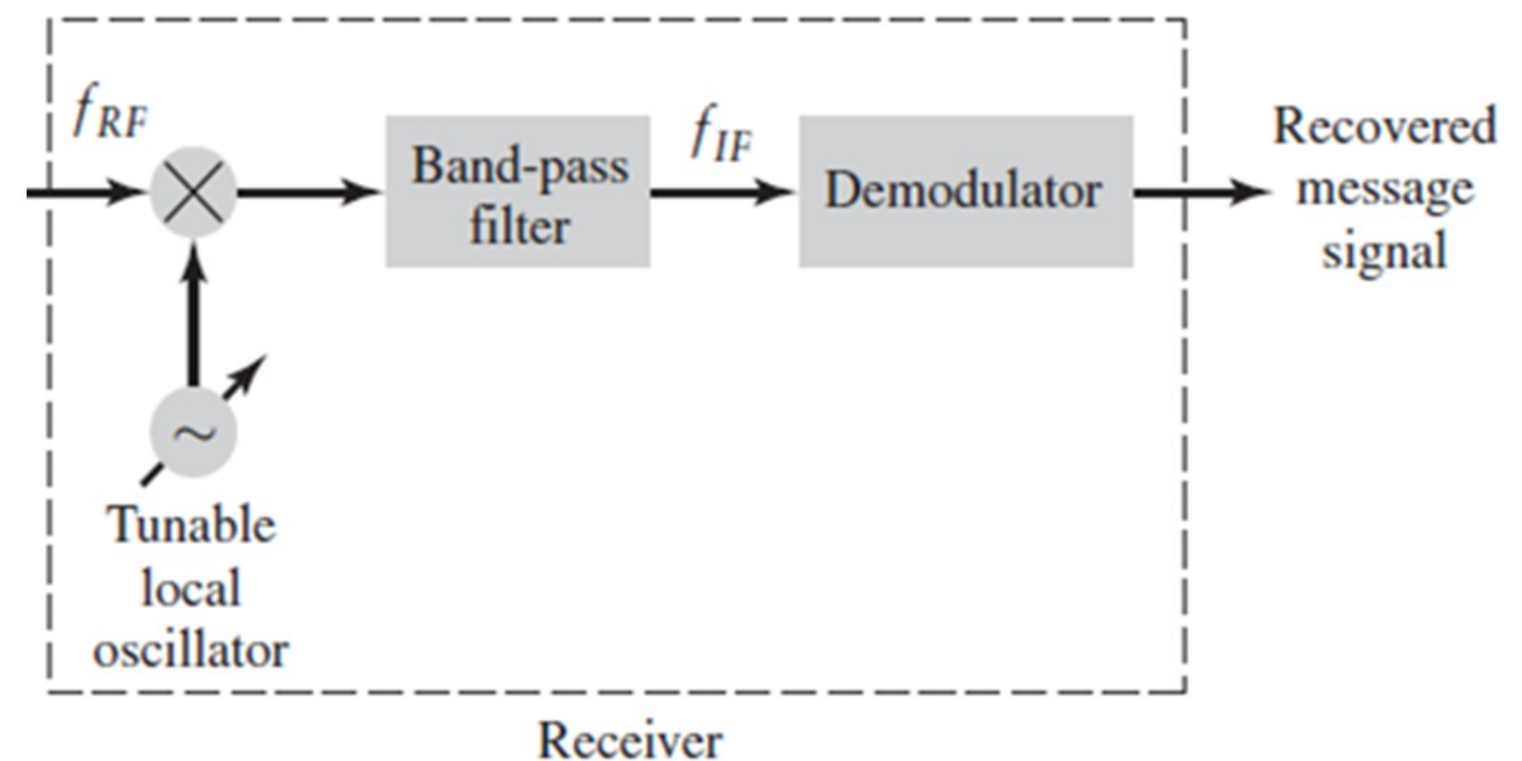


FIGURE 9.5 Block diagram of band-pass transmission showing a superheterodyne receiver.

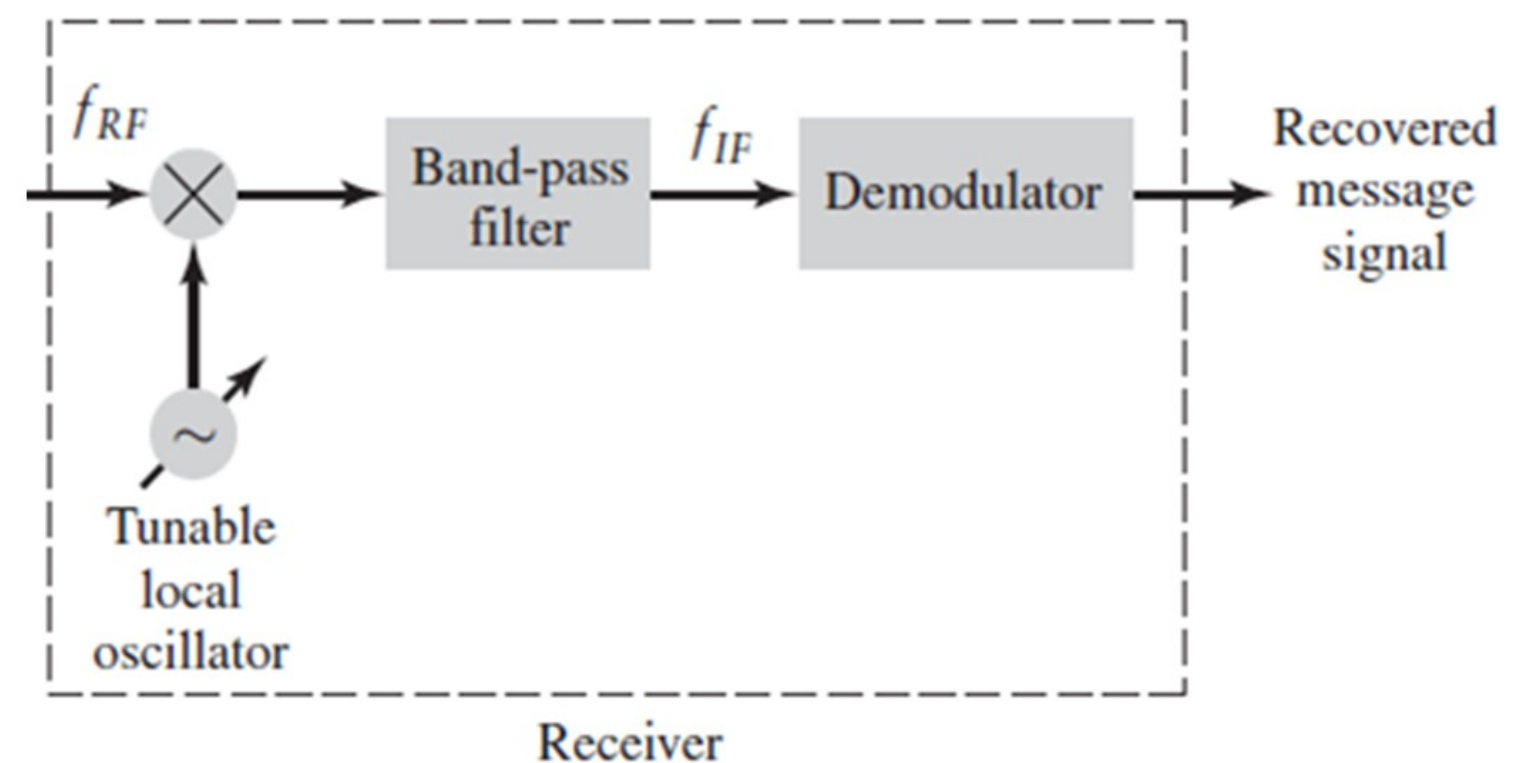
9.3: Band-Pass Receiver Structures

- The *filter before* the local oscillator is centered at a higher RF frequency and is usually much wider, wide enough to encompass all RF channels that the receiver is intended to handle
- **For example**, with an FM receiver the band-pass filter before the local oscillator would pass the frequencies from 88 to 108 MHz



9.3: Band-Pass Receiver Structures

- The *band-pass filter after* the oscillator passes the signal of a single RF channel relatively undistorted but limits the noise to those components within the passband of the filter.
- With the same FM receiver, the band-pass filter after the local oscillator would be approximately 200 kHz wide; *it is the effects of this narrower filter that are of most interest to us*



Section 9.4: Noise in Linear Receivers Using Coherent Detection

9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme:

- In the case of double side band suppressed-carrier (DSB-SC) modulation, the modulated signal is represented as

$$s(t) = A_c m(t) \cos(2\pi f_c t + \theta)$$

- Where f_c is the carrier frequency, and $\mathbf{m(t)}$ is the message signal; the carrier phase θ is a random variable, but not varying during the course of transmission

9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme:

- For suppressed-carrier signals, linear coherent detection was identified as the proper demodulation strategy

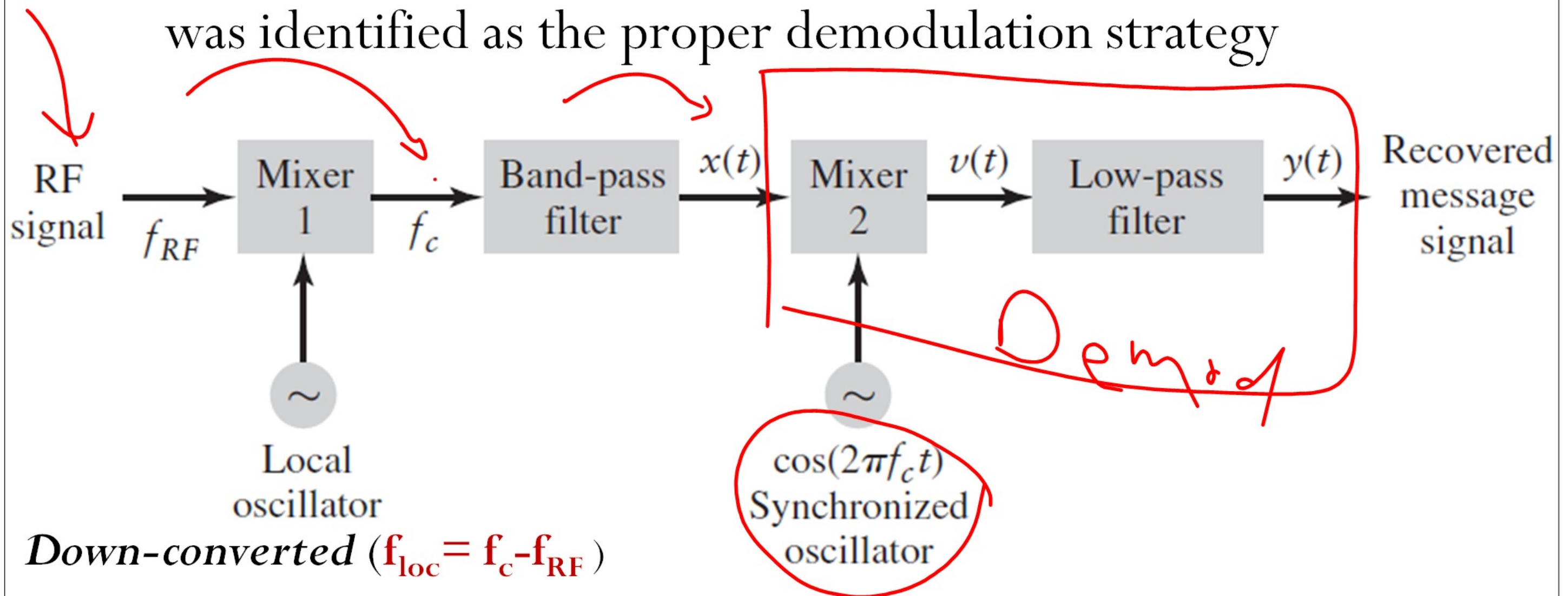


FIGURE 9.6 A linear DSB-SC receiver using coherent demodulation.

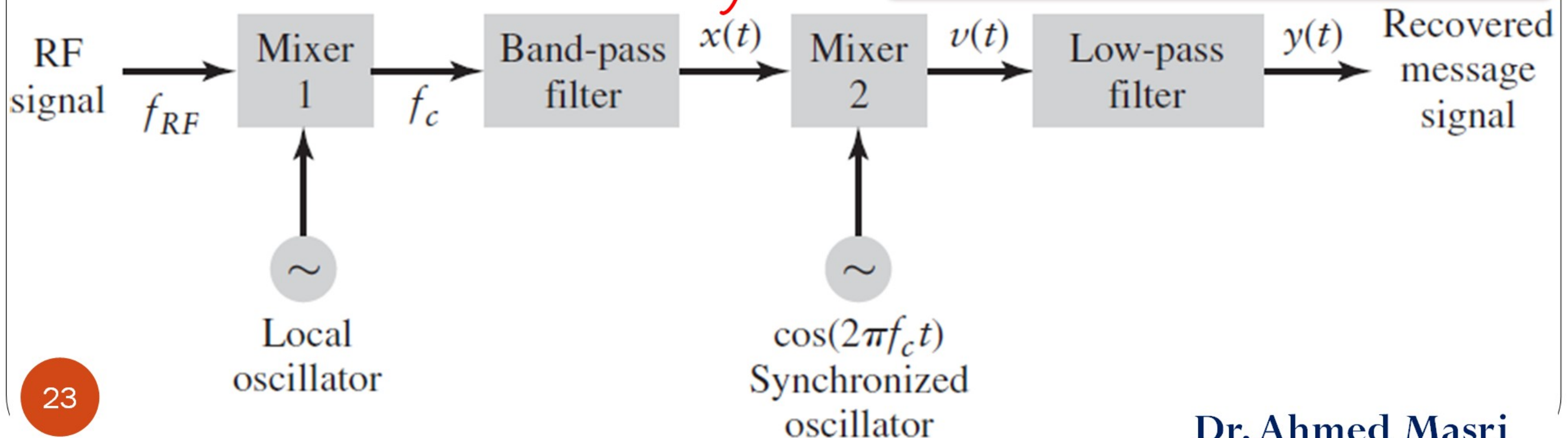
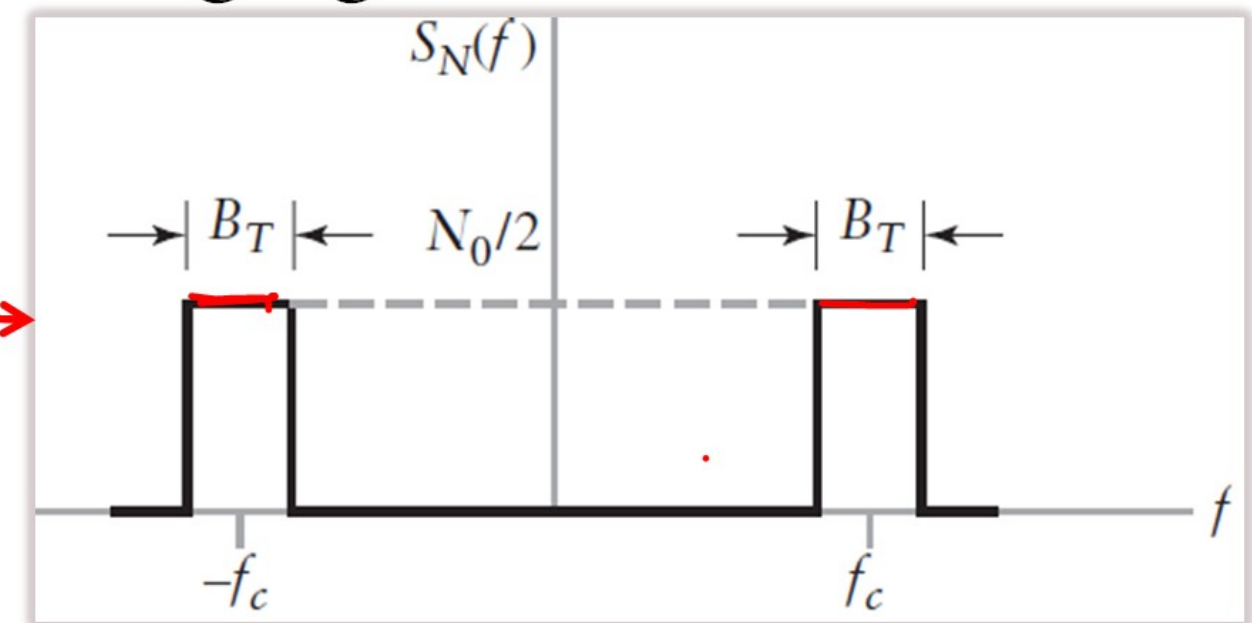
9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme:

- After band-pass filtering, the resulting signal is

$$x(t) = s(t) + n(t)$$

$$s(t) + w(t)$$



9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: Pre-detection SNR

- The average power of the signal $s(t)$:
 - Since the carrier and modulating signal are independent, this can be broken down into two components as follows:

$$E[s^2(t)] = E[(A_c \cos(2\pi f_c t + \theta))^2] E[m^2(t)]$$

- If we let

$$P = E[m^2(t)]$$

be the average signal (message) power and using the result of Example “SNR of sinusoidal”

$$E[s^2(t)] = \frac{A_c^2 P}{2}$$

9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: Pre-detection SNR

- If the band-pass filter has a noise bandwidth B_T then the noise power passed by this filter is $N_0 B_T$ by definition
- Consequently, the signal-to-noise ratio of the signal is

$$\text{SNR}_{\text{pre}}^{\text{DSB}} = \frac{A_c^2 P}{2N_0 B_T}$$

- This is the *pre-detection signal-to-noise ratio* of the DSB-SC system *because* it is measured at a point in the system *before* the message signal $\mathbf{m(t)}$ is demodulated

9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: Post-detection SNR

- The post-detection signal-to-noise ratio is the ratio of the message signal power to the noise power *after* demodulation/detection
- The post-detection SNR depends on both the modulation and demodulation techniques

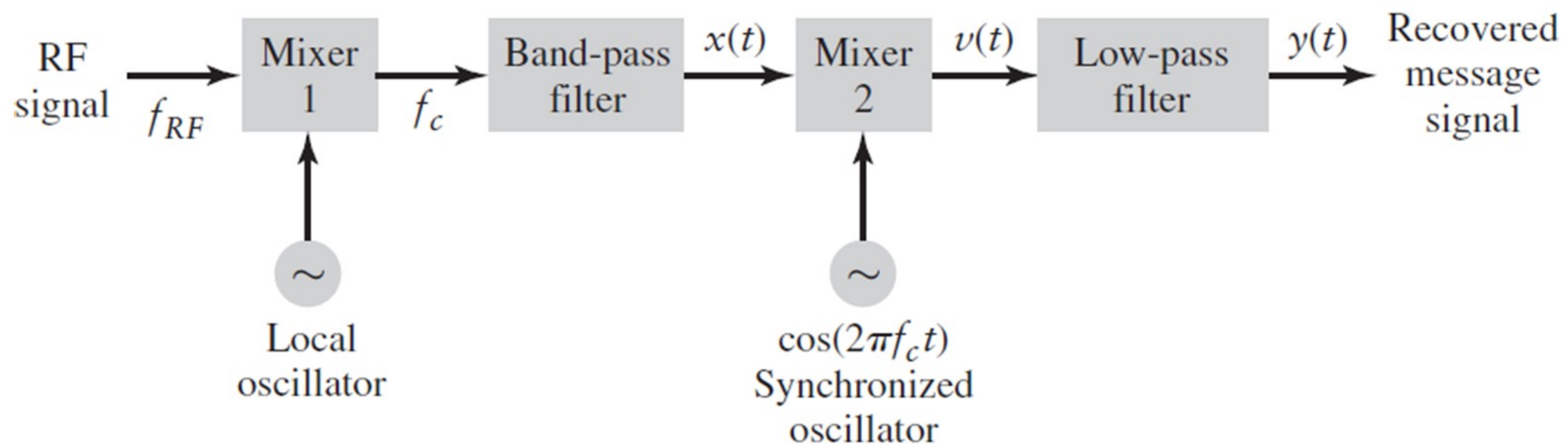
9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: Post-detection SNR

- Using the narrowband representation of the band-pass noise, the signal at the input to the coherent detector

$$x(t) = s(t) + n_I(t) \cos(2\pi f_c t) - n_Q(t) \sin(2\pi f_c t)$$

- where $n_I(t)$ and $n_Q(t)$ are the in-phase and quadrature components of $n(t)$ with respect to the carrier



9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: Post-detection SNR

- The output of mixer 2

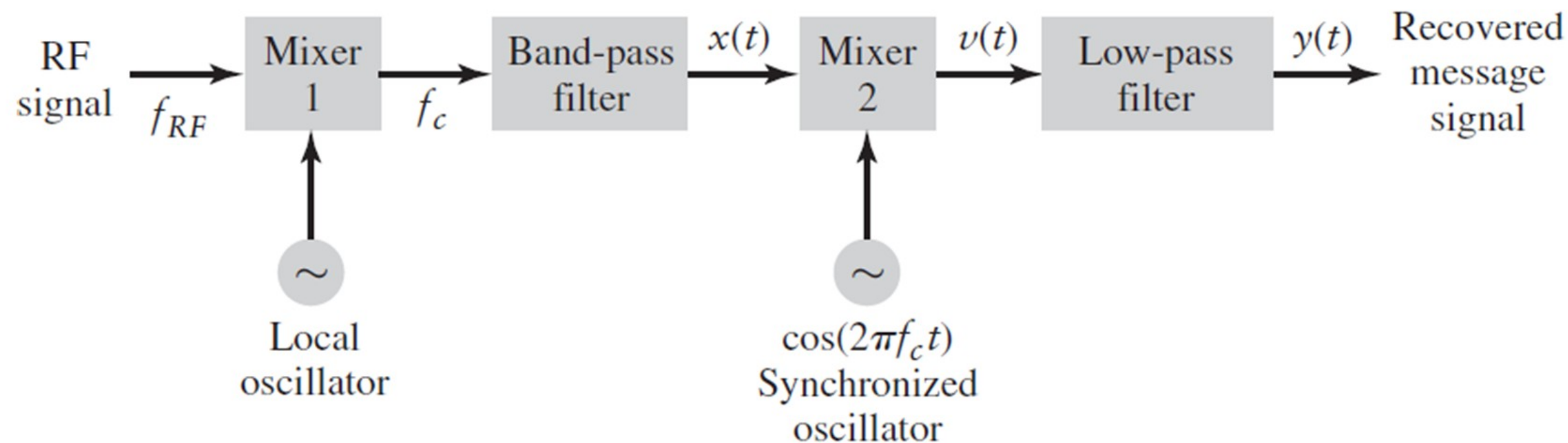
$$\cos A \cos A = \frac{1 + \cos 2A}{2}$$

$$\sin A \cos A = \frac{\sin 2A}{2}$$

$$v(t) = x(t) \cos(2\pi f_c t)$$

$$= \frac{1}{2}(A_c m(t) + n_I(t))$$

$$+ \frac{1}{2}(A_c m(t) + n_I(t)) \cos(4\pi f_c t) - \frac{1}{2}n_Q(t) \sin(4\pi f_c t)$$



9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: **Post-detection SNR**

$$= \frac{1}{2}(A_c m(t) + n_I(t)) + \frac{1}{2}(A_c m(t) + n_I(t)) \cos(4\pi f_c t) - \frac{1}{2}n_Q(t) \sin(4\pi f_c t)$$

- The first part represents the *baseband signal* and *in-phase component of the noise*, while the second part represents *quadrature component* of its noise centered at the much higher frequency of $2f_c$
- These high-frequency components are removed with a low-pass filter

$$y(t) = \frac{1}{2}(A_c m(t) + n_I(t))$$

9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: **Post-detection SNR**

Two observations can be made:

$$y(t) = \frac{1}{2}(A_c m(t) + n_I(t))$$

- The message signal and the in-phase component of the filtered noise appear additively in the output.
- The quadrature component of the noise is completely rejected by the demodulator.

9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: Post-detection SNR

Now we may compute the output or post-detection signal to noise ratio by noting the following:

- 1) The message component $\frac{1}{2}A_c m(t)$ is so analogous to the computation of the predetection signal power, the post-detection signal power is $\frac{1}{4}A_c^2 P$ where P is the average message power as defined $P = E[m^2(t)]$

9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: Post-detection SNR

- 2) The noise component $\frac{1}{2}n_I(t)$ is after low-pass filtering. The in-phase component has a noise spectral density of N_0 over the bandwidth from $-B_T/2$ to $B_T/2$
- If the low-pass filter has a noise bandwidth W , corresponding to the message bandwidth, which is less than or equal to $B_T/2$ then the output noise power is

$$\begin{aligned} E[n_I^2(t)] &= \int_{-W}^W N_0 df \\ &= 2N_0 W \end{aligned}$$

- Thus the power in $n_I(t)$ is $2N_0 W$.

9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: Post-detection SNR

- Combining these observations, we obtain the post-detection SNR of

$$\text{SNR}_{\text{post}}^{\text{DSB}} = \frac{\frac{1}{4}(A_c^2)P}{\frac{1}{4}(2N_0 W)} = \frac{A_c^2 P}{2N_0 W}$$

- Consequently, if $W \approx B_T/2$, the post-detection SNR is *twice* the pre-detection SNR.
- This is due to the fact that the quadrature component of the noise has been discarded by the synchronous demodulator.*

9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme: Figure Of Merit

- It should be clear that for the reference transmission model defined in Section 9.2, the average noise power for a message of bandwidth W is N_0W
- For DSB-SC modulation the average modulated message power is given by

$$E[s^2(t)] = \frac{A_c^2 P}{2}$$
- Consequently the reference SNR for this transmission scheme is $SNR_{ref} = A_c^2 P / (2N_0W)$

$$\text{Figure of merit} = \frac{SNR_{\text{post}}^{\text{DSB}}}{SNR_{\text{ref}}} = 1$$

9.4: Noise in Linear Receivers Using Coherent Detection

Noise in DSB-SC modulation scheme

- This illustrates that we lose nothing in performance by using a band-pass modulation scheme compared to the baseband modulation scheme, even though the bandwidth of the former is twice as wide
- Consequently, DSB-SC modulation provides a *baseline* against which we may compare other amplitude modulation detection schemes.

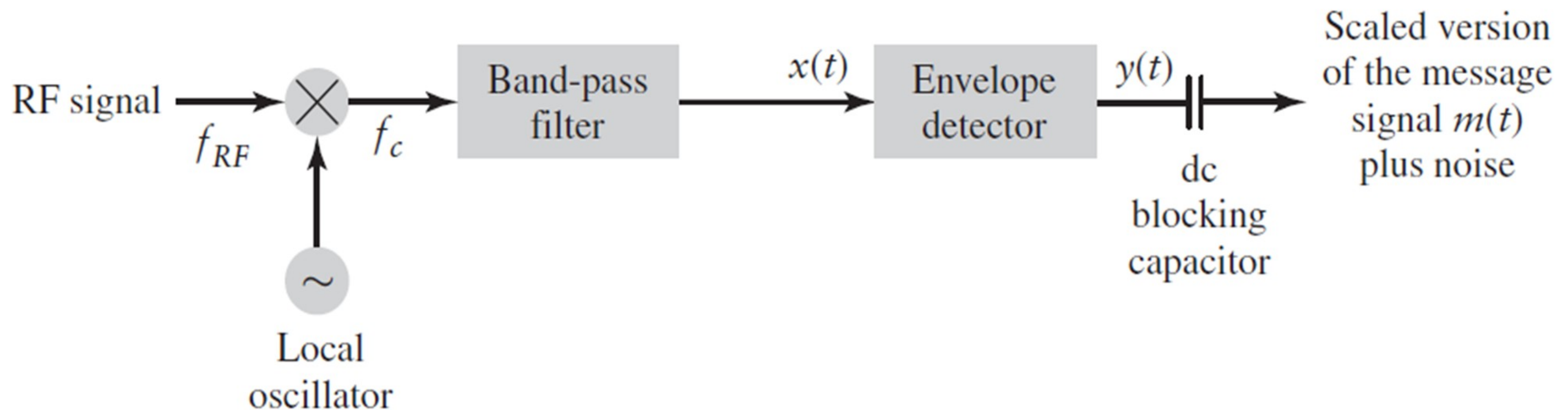
Section 9.5: Noise In AM Receivers Using Envelope Detection

9.5: Noise In AM Receivers Using Envelope Detection

- The envelope-modulated signal is represented by

$$s(t) = A_c(1 + k_a m(t)) \cos(2\pi f_c t)$$

- Where k_a is the amplitude sensitivity of the modulator
- Model of AM receiver using envelope detection



9.5: Noise In AM Receivers Using Envelope Detection

PRE-DETECTION SNR

$$s(t) = A_c(1 + k_a m(t)) \cos(2\pi f_c t)$$

- The average power of the carrier component is $A_c^2/2$ due to the sinusoidal nature of the carrier
- The power in the modulated part of the signal is

$$\begin{aligned} E[(1 + k_a m(t))^2] &= E[1 + 2k_a m(t) + k_a^2 m^2(t)] \\ &= 1 + 2k_a E[m(t)] + k_a^2 E[m^2(t)] \\ &= 1 + k_a^2 P \end{aligned}$$

Where we assume the message signal has zero mean

$$E[m(t)] = 0$$

9.5: Noise In AM Receivers Using Envelope Detection

PRE-DETECTION SNR

- Consequently, the received signal power is $A_c^2(1+k_a^2P)/2$
- The *pre-detection signal-to-noise ratio* is given by

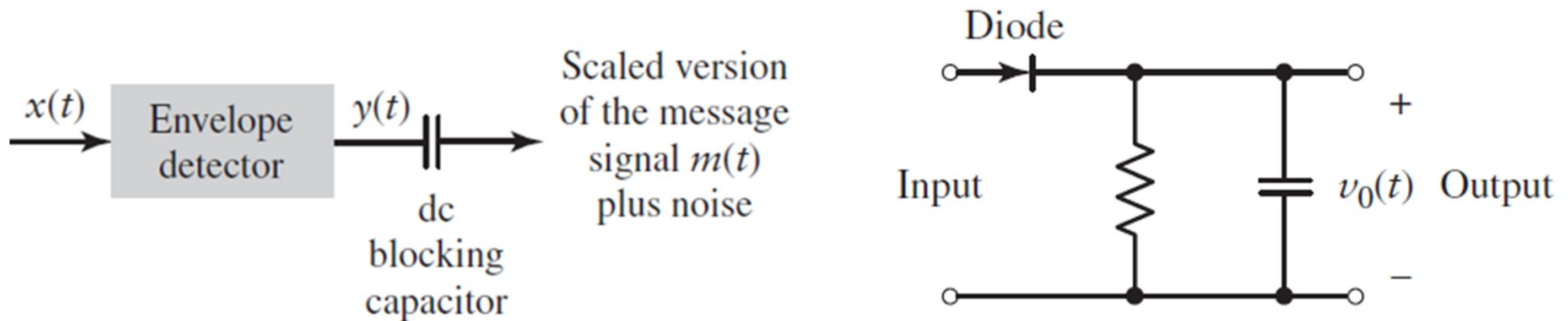
$$\text{SNR}_{\text{pre}}^{\text{AM}} = \frac{A_c^2(1 + k_a^2P)}{2N_0B_T}$$

where B_T is the noise bandwidth of the band-pass filter

9.5: Noise In AM Receivers Using Envelope Detection

POST-DETECTION SNR

- To determine the post-detection signal-to-noise ratio, we must analyze the effects of the remainder of the envelope detector

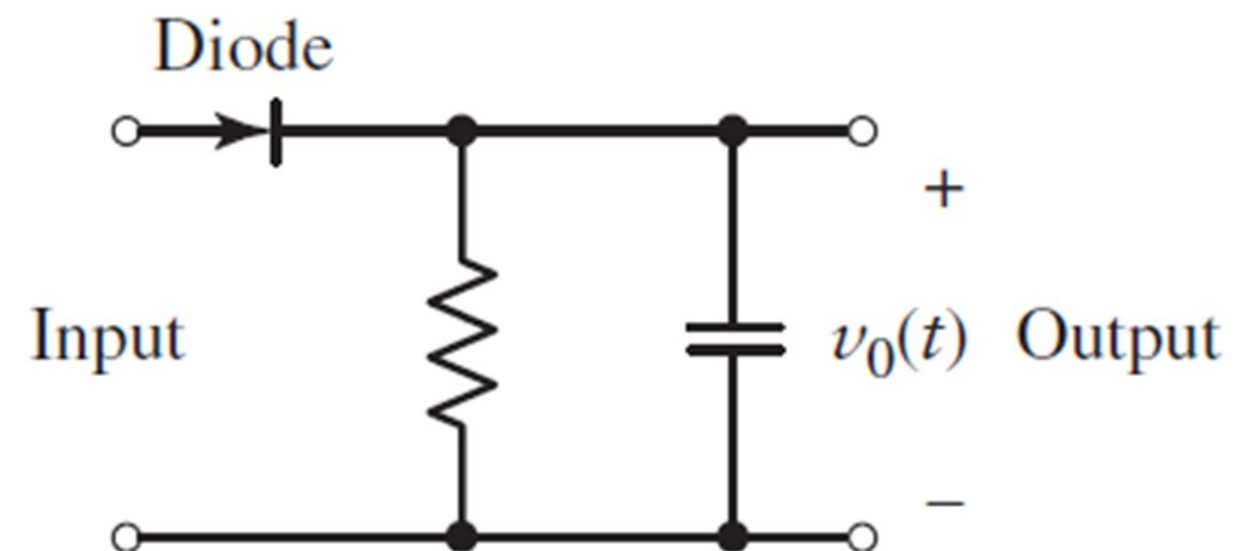
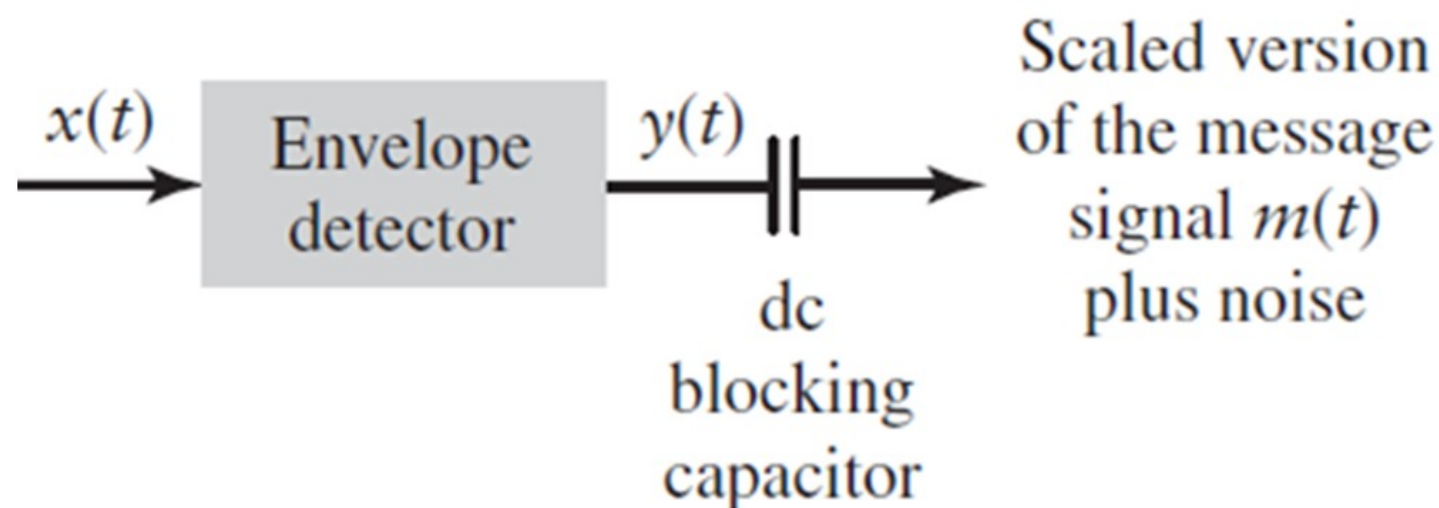


9.5: Noise In AM Receivers Using Envelope Detection

POST-DETECTION SNR

- We can represent the noise in terms of its in-phase and quadrature components, and consequently model the input to the envelope detector as

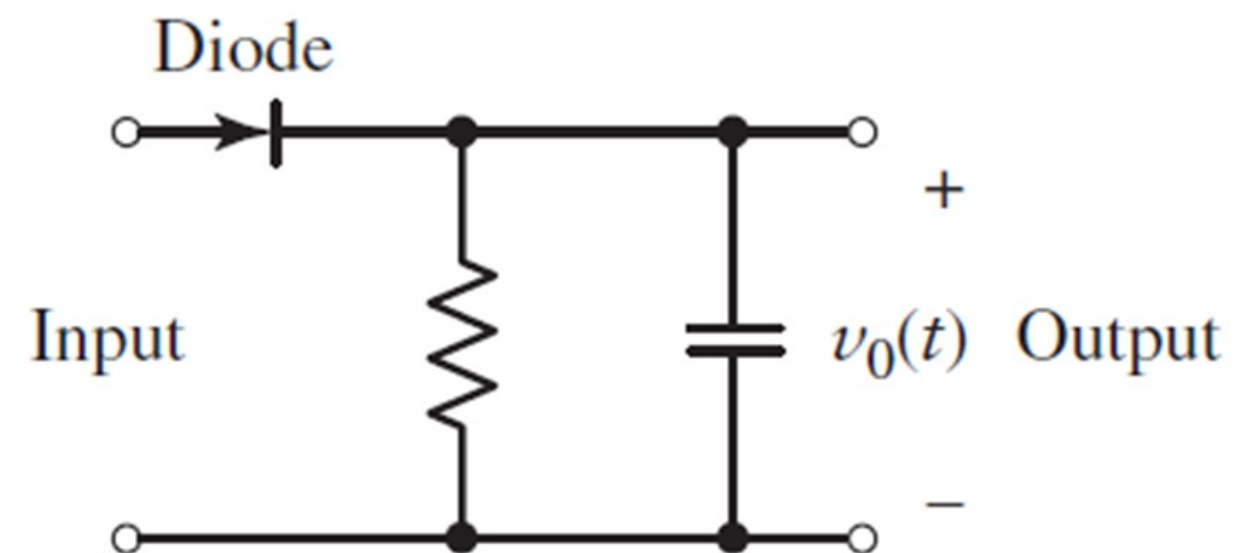
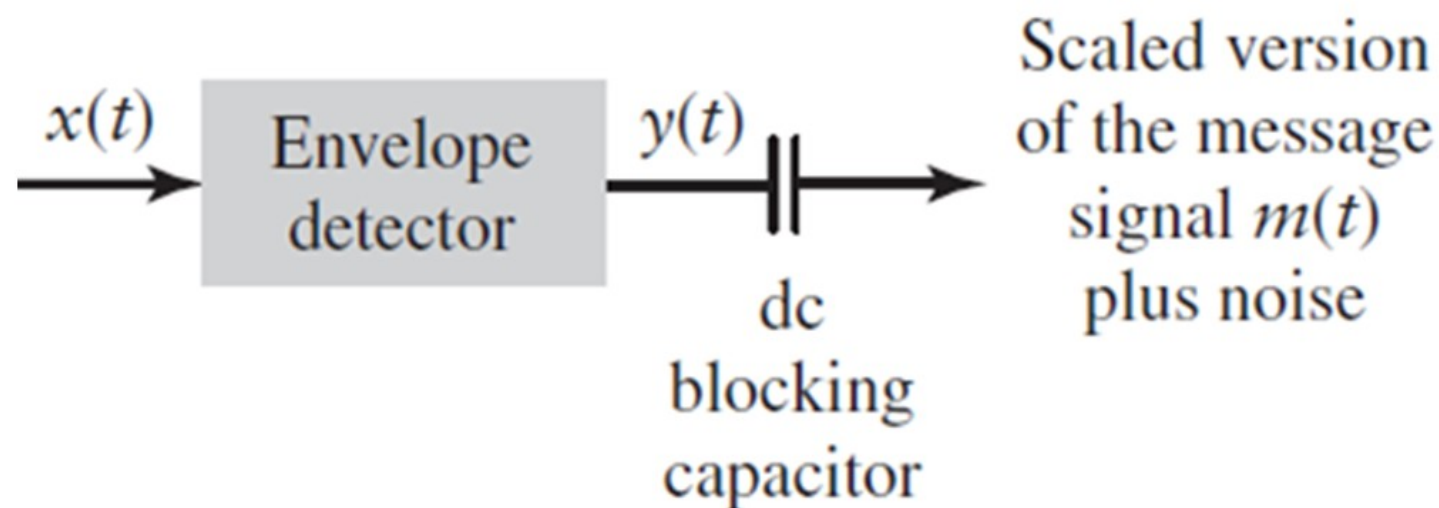
$$\begin{aligned}
 x(t) &= s(t) + n(t) \\
 &= [A_c + A_c k_a m(t) + n_I(t)] \cos(2\pi f_c t) - n_Q(t) \sin(2\pi f_c t)
 \end{aligned}$$



9.5: Noise In AM Receivers Using Envelope Detection

POST-DETECTION SNR

- The object of the envelope detector is to recover the *low-frequency amplitude* variations of the *high-frequency signal*



9.5: Noise In AM Receivers Using Envelope Detection

POST-DETECTION SNR

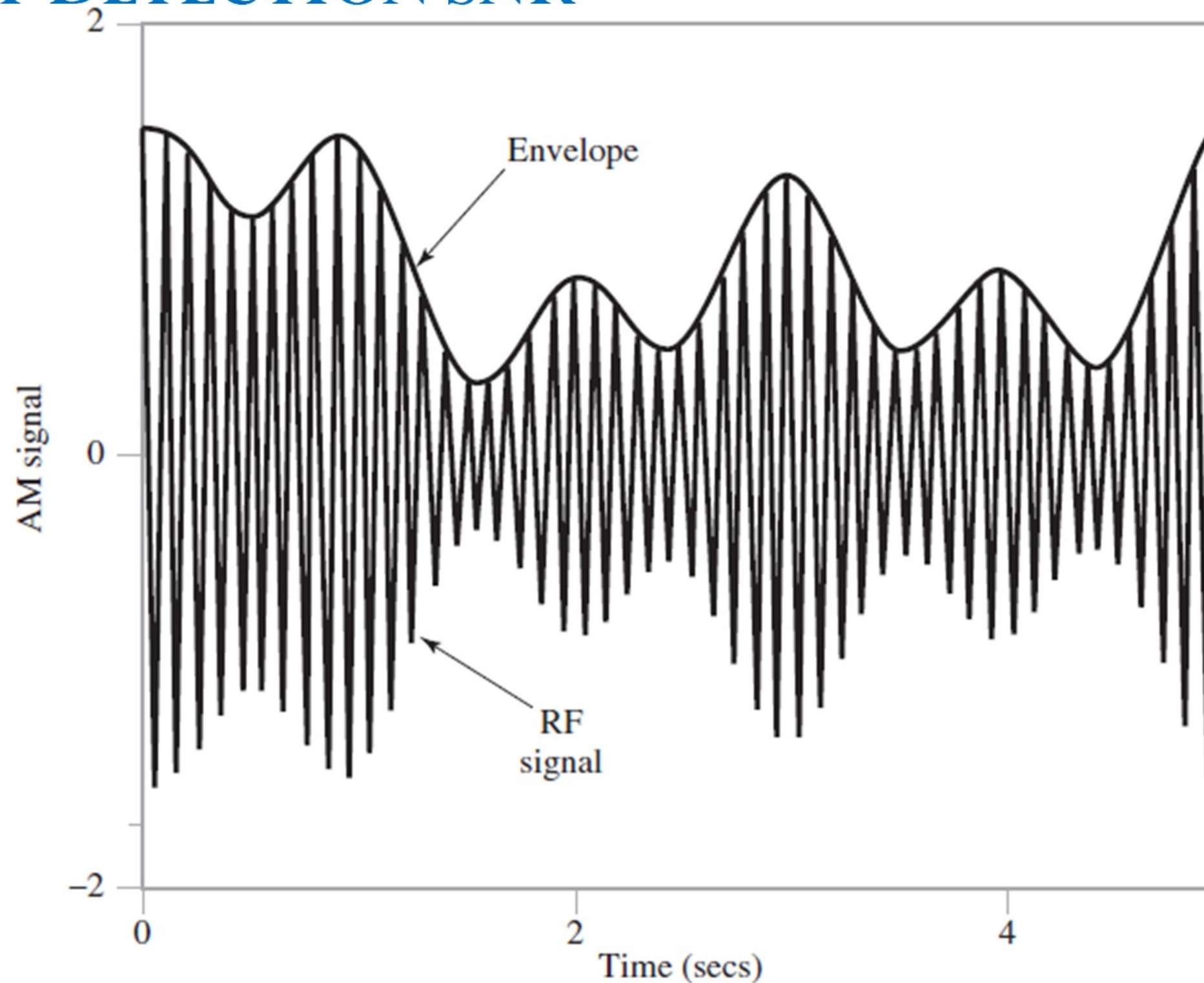


FIGURE 9.10 Illustration of envelope on high-frequency carrier.

9.5: Noise In AM Receivers Using Envelope Detection

POST-DETECTION SNR

Using Phasor Diagram for representation

- The signal component of the phasor is $A_c(1+k_a m(t))$, and the noise has two orthogonal phasor components, $n_I(t)$ and $n_Q(t)$

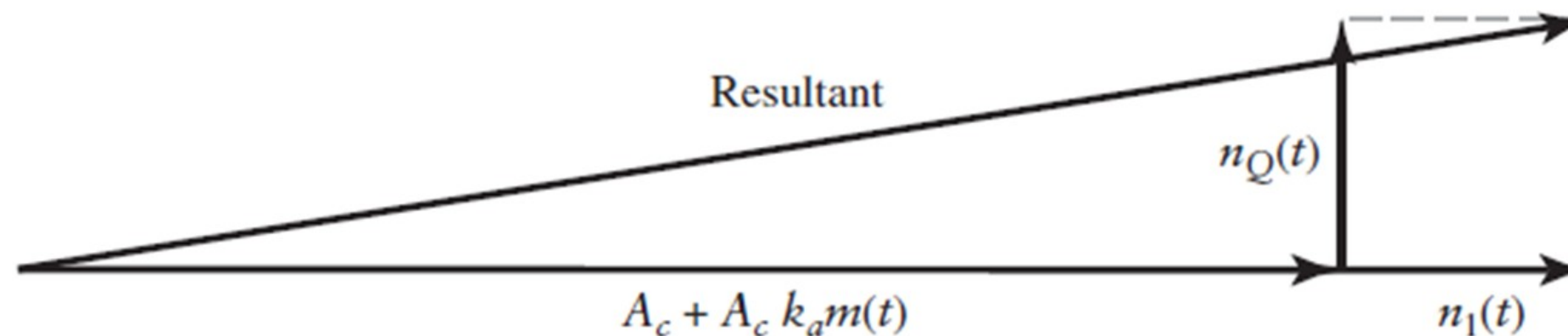


FIGURE 9.11 Phasor diagram for AM wave plus narrowband noise.

9.5: Noise In AM Receivers Using Envelope Detection

POST-DETECTION SNR

- The output of the envelope detector is the amplitude of the phasor representing $x(t)$ and it is given by

$$y(t) = \text{envelope of } x(t)$$

$$= \{[A_c(1 + k_a m(t)) + n_I(t)]^2 + n_Q^2(t)\}^{1/2}$$

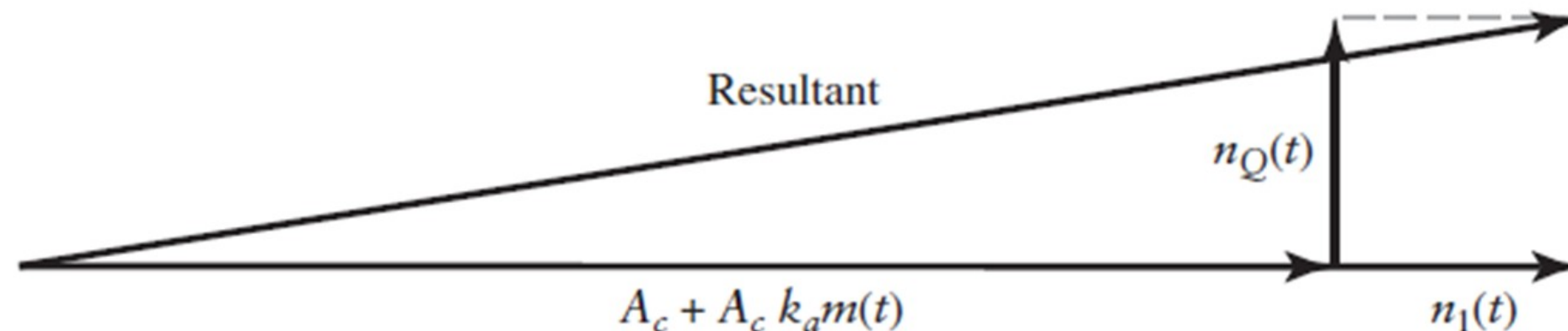


FIGURE 9.11 Phasor diagram for AM wave plus narrowband noise.

9.5: Noise In AM Receivers Using Envelope Detection

POST-DETECTION SNR

$$\begin{aligned} y(t) &= \text{envelope of } x(t) \\ &= \{[A_c(1 + k_a m(t)) + n_I(t)]^2 + n_Q^2(t)\}^{1/2} \end{aligned}$$

If we assume that the signal is much larger than the noise then

- Using the approximation $\sqrt{A^2 + B^2} \approx A$ when $A \gg B$, we may write

$$y(t) \approx A_c + A_c k_a m(t) + n_I(t)$$

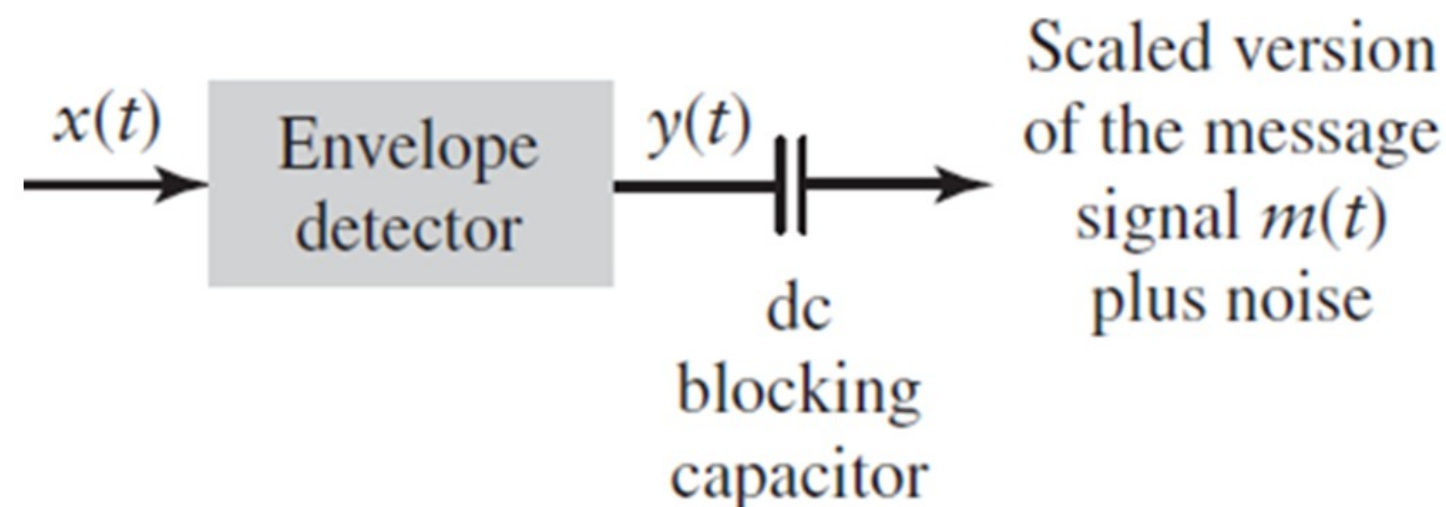
9.5: Noise In AM Receivers Using Envelope Detection

POST-DETECTION SNR

$$y(t) \approx A_c + A_c k_a m(t) + n_I(t)$$

This new expression for the demodulated signal has three components: *dc component*, *signal component*, and *noise component*

- The dc term can be removed with a capacitor



9.5: Noise In AM Receivers Using Envelope Detection

POST-DETECTION SNR

$$y(t) \approx A_c k_a m(t) + n_I(t)$$

Accordingly, the post-detection SNR for the envelope detection of AM, using a message bandwidth W , is given by

$$\text{SNR}_{\text{post}}^{\text{AM}} = \frac{A_c^2 k_a^2 P}{2N_0 W}$$

Where the numerator represents the average power of the message $A_c k_a m(t)$ and the denominator represents the average power of $n_I(t)$

9.5: Noise In AM Receivers Using Envelope Detection

POST-DETECTION SNR

$$\text{SNR}_{\text{post}}^{\text{AM}} = \frac{A_c^2 k_a^2 P}{2N_0 W}$$

This evaluation of the output SNR is only valid under two conditions:

1. The SNR is high (signal power is high compared with noise power).
 2. k_a is adjusted for *100% modulation or less*, so there is no distortion of the signal envelope
- As with suppressed-carrier amplitude modulation, the message bandwidth W is approximately one-half of the transmission bandwidth B_T

9.5: Noise In AM Receivers Using Envelope Detection

FIGURE OF MERIT

For AM modulation, the average transmitted power is given by

$$(1 + k_a^2 P) A_c^2 / 2$$

- Consequently, the reference **SNR** is $A_c^2 (1 + k_a^2 P) / (2N_0 W)$
- The figure of merit for this AM modulation– demodulation scheme is

$$\text{Figure of merit} = \frac{\text{SNR}_{\text{post}}^{\text{AM}}}{\text{SNR}_{\text{ref}}} = \frac{k_a^2 P}{1 + k_a^2 P}$$

9.5: Noise In AM Receivers Using Envelope Detection

FIGURE OF MERIT

$$\text{Figure of merit} = \frac{\text{SNR}_{\text{post}}^{\text{AM}}}{\text{SNR}_{\text{ref}}} = \frac{k_a^2 P}{1 + k_a^2 P}$$

- Since the product is always *less than unity* (otherwise the signal would be over modulated), the figure of merit for this system is *always less than 0.5*
- Hence, the noise performance of an envelope-detector receiver is always lower than a DSB-SC receiver
- The reason is that at least half of the power is wasted transmitting the *carrier as a component* of the modulated (transmitted) signal.

Section 9.6: Noise in SSB Receivers

9.6: Noise in SSB Receivers

- We assume that only the *lower sideband* is transmitted, so that we may express the modulated wave as

$$s(t) = \frac{A_c}{2} m(t) \cos(2\pi f_c t) + \frac{A_c}{2} \hat{m}(t) \sin(2\pi f_c t)$$

Observations:

1. The two components $m(t)$ and $\hat{m}(t)$ are *uncorrelated* with each other. Therefore, their power spectral densities are *additive*.
2. The Hilbert transform $\hat{m}(t)$ is obtained by passing $m(t)$ through a linear filter with transfer function $-j\text{sgn}(f)$. The squared magnitude of this transfer function *is equal to one* for all f . Accordingly, *$m(t)$ and $\hat{m}(t)$ have the same average power*

9.6: Noise in SSB Receivers

- Thus, proceeding in a manner similar to that for the DSB-SC receiver, we find that:
- The in-phase and quadrature components of the SSB modulated wave $s(t)$ contribute an average power of $A_c^2 P / 8$ each.
- The average power of $s(t)$ is therefore $A_c^2 P / 4$.
- This result is *half* that of the DSB-SC case, which is intuitively satisfying.

9.6: Noise in SSB Receivers

PRE-DETECTION SNR

- For the SSB signal, the transmission bandwidth B_T is approximately equal to the message bandwidth W
- Consequently, using the signal power calculation of the previous section, the pre-detection signal-to-noise ratio of a coherent receiver with SSB modulation is

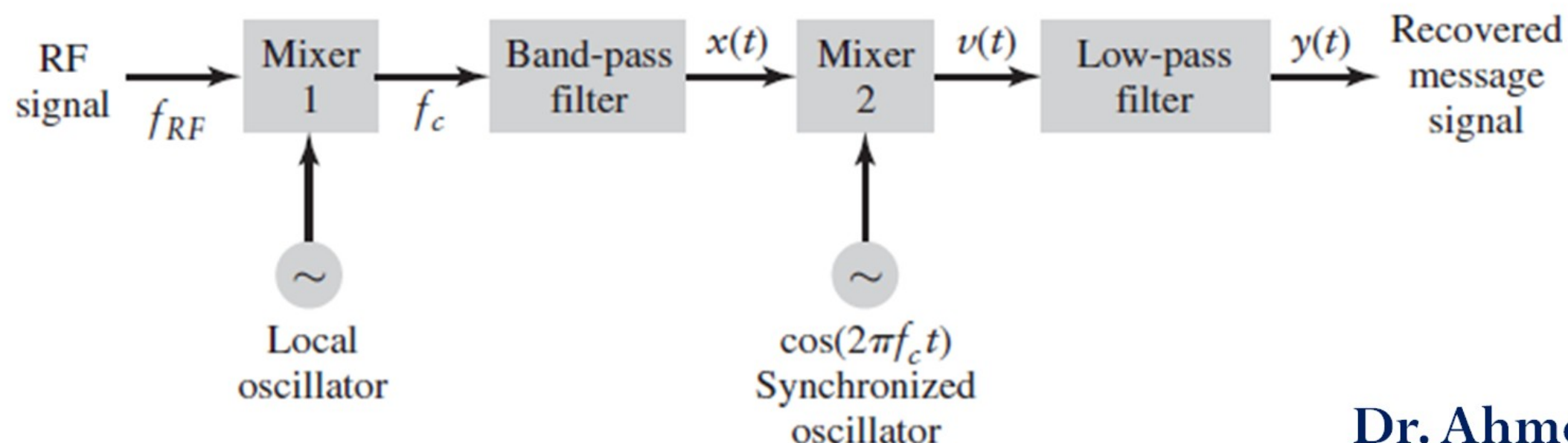
$$\text{SNR}_{\text{pre}}^{\text{SSB}} = \frac{A_c^2 P}{4N_0 W}$$

9.6: Noise in SSB Receivers

POST-DETECTION SNR

- Using the same superheterodyne receiver, the band-pass signal after multiplication with the synchronous oscillator output $\cos(2\pi f_c t)$ is

$$\begin{aligned}
 v(t) &= x(t) \cos(2\pi f_c t) \\
 &= \frac{1}{2} \left(\frac{A_c}{2} m(t) + n_I(t) \right) + \frac{1}{2} \left(\frac{A_c}{2} m(t) + n_I(t) \right) \cos(4\pi f_c t) - \frac{1}{2} \left(\frac{A_c}{2} \hat{m}(t) + n_Q(t) \right) \sin(4\pi f_c t)
 \end{aligned}$$



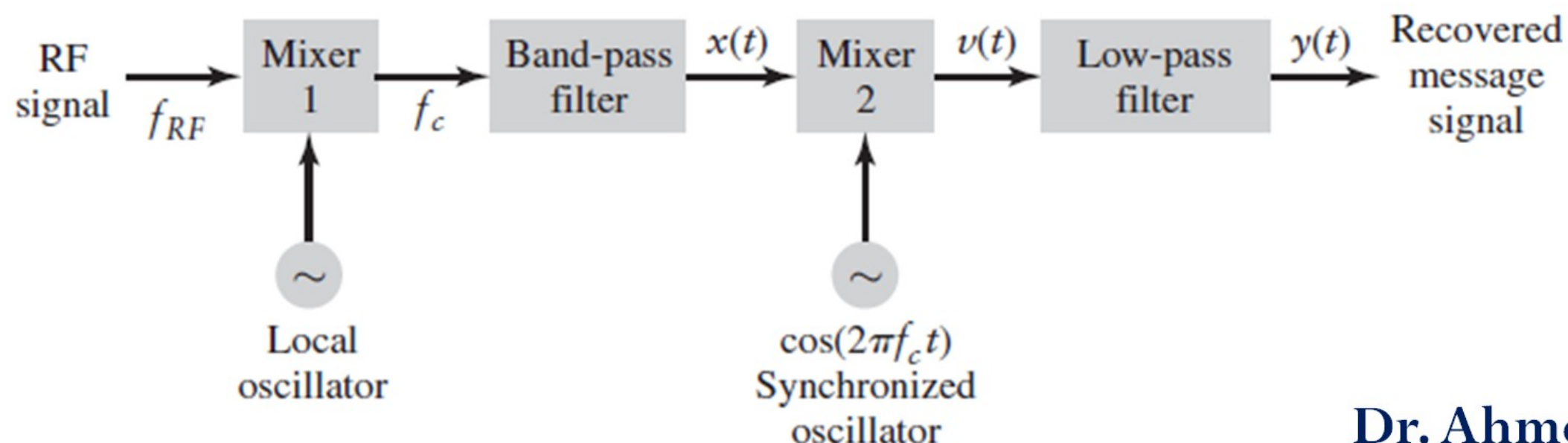
9.6: Noise in SSB Receivers

POST-DETECTION SNR

- After low-pass filtering the $v(t)$ we are left with

$$y(t) = \frac{1}{2} \left(\frac{A_c}{2} m(t) + n_I(t) \right)$$

- As expected, we see that the quadrature component $\hat{m}(t)$ of the message signal has been eliminated from the detector output



9.6: Noise in SSB Receivers

POST-DETECTION SNR

- The band-pass noise $n(t)$ will also be of single sideband nature
- The spectrum of the in-phase component of the noise $n_I(t)$ is given by (from section 8, Eq. (8.98))

$$S_{N_I}(f) = \begin{cases} S_N(f - f_c) + S_N(f + f_c), & -B \leq f \leq B \\ 0, & \text{otherwise} \end{cases}$$

9.6: Noise in SSB Receivers

POST-DETECTION SNR

- For the single sideband case, $S_N(f)$ is $N_0/2$ for $f_c < f < f_c + W$ and for $-f_c - W < f < -f_c$, Consequently,

$$S_{N_I}(f) = \begin{cases} \frac{N_0}{2}, & -W \leq f \leq W \\ 0, & \text{otherwise} \end{cases}$$

- The spectral density of is double-sided, as in the DSB-SC case, but with half of the power

9.6: Noise in SSB Receivers

POST-DETECTION SNR

$$y(t) = \frac{1}{2} \left(\frac{A_c}{2} m(t) + n_I(t) \right)$$

- The message component in the receiver output is $A_c m(t) / 4$, for that the average power of the recovered message is $A_c^2 P / 16$
- The corresponding noise power $\frac{1}{4} N_0 W$

$$\text{SNR}_{\text{post}}^{\text{SSB}} = \frac{A_c^2 P}{4 N_0 W}$$

9.6: Noise in SSB Receivers

FIGURE OF MERIT

- The average signal power for the SSB system, as discussed above, is $A_c^2 P / 4$
- Consequently, the reference SNR is $A_c^2 P / (4N_0 W)$
- The figure of merit for the SSB system is the ratio of

$$\text{Figure of merit} = \frac{\text{SNR}_{\text{post}}^{\text{SSB}}}{\text{SNR}_{\text{ref}}} = 1$$

- Consequently, SSB transmission has the same figure of merit as DSB-SC.
- The performance of vestigial sideband with coherent detection is similar to that of SSB.

9.6: Noise in SSB Receivers

Comparison:

- DSB-SC provides the same SNR performance as the baseband reference model but requires synchronization to perform coherent detection
- AM-LC simplifies the receiver design significantly as it is implemented with an envelope detector. However, AM-LC requires significantly more transmitter power to obtain the same SNR performance as the baseband reference model
- SSB-SC achieves the same SNR performance as the baseband reference model but only requires half the transmission bandwidth of the DSC-SC system. On the other hand, SSB requires more transmitter processing

Section 9.7: Detection of Frequency Modulation (FM)

9.7: Detection of Frequency Modulation (FM)

- Recall from Section 4.1 that the frequency-modulated signal is given by

$$s(t) = A_c \cos \left[2\pi f_c t + 2\pi k_f \int_0^t m(\tau) d\tau \right] \quad (9.40)$$

- The received FM signal has a carrier frequency f_c and a transmission bandwidth B_T such that a negligible amount of power lies outside the frequency band $f_c \pm B_T/2$ for positive frequencies, and similarly for negative frequencies.

9.7: Detection of Frequency Modulation (FM)

PRE-DETECTION SNR

- For FM detection, we assume a receiver model as shown in

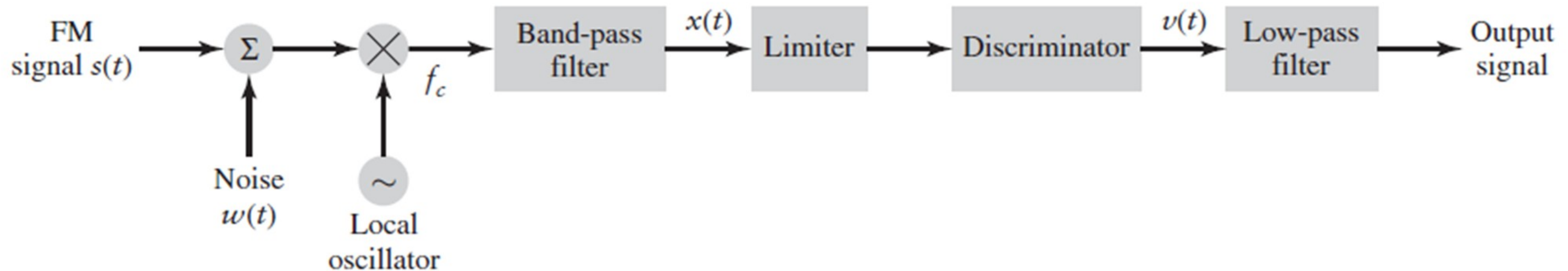


FIGURE 9.13 Model of an FM receiver.

- we assume that the noise is a white zero-mean Gaussian process with power spectral density $N_0/2$

9.7: Detection of Frequency Modulation (FM)

- The bandpass filter has a center frequency f_c and bandwidth B_T so that it passes the FM signal without distortion.
- Ordinarily, B_T is small compared with the center frequency so that we may use the narrowband $\mathbf{n}(t)$ representation for the filtered version of the channel noise $\mathbf{w}(t)$

9.7: Detection of Frequency Modulation (FM)

- The *pre-detection SNR* in this case is simply the carrier power $A_c^2/2$ divided by the noise passed by the bandpass filter, $N_0 B_T$; namely,

$$\text{SNR}_{\text{pre}}^{\text{FM}} = \frac{A_c^2}{2N_0 B_T}$$

9.7: Detection of Frequency Modulation (FM)

- In an FM system, the message signal is embedded in the variations of *the instantaneous frequency* of the carrier
- The amplitude of the carrier is *constant*.
- *Therefore* any variations of the carrier amplitude at the receiver input must result from *noise* or *interference*
- The amplitude *limiter*, following the band-pass filter in the receiver model of Fig. 9.13, is used *to remove amplitude variations by clipping the modulated wave*

9.7: Detection of Frequency Modulation (FM)

- The resulting wave is almost rectangular
- This wave is rounded by another band-pass filter that is an integral part of the limiter, thereby suppressing harmonics of the carrier frequency that are caused by the clipping.

9.7: Detection of Frequency Modulation (FM)

The discriminator in the model of Fig. 9.13 consists of two components

1. *A slope network or differentiator:* It produces a hybrid-modulated wave in which both amplitude and frequency vary in accordance with the message signal.
2. *An envelope detector* that recovers the amplitude variation and reproduces the message signal.

9.7: Detection of Frequency Modulation (FM)

- The post-detection filter, labeled “*low-pass filter*” in Fig. 9.13, has a bandwidth that is just large enough to pass the highest frequency component of the message signal
- This filter removes the out-of-band components of the noise at the discriminator output and thereby keeps the effect of the output noise to a minimum

9.7: Detection of Frequency Modulation (FM)

POST-DETECTION SNR

- The noisy FM signal after band-pass filtering may be represented as

$$x(t) = s(t) + n(t) \quad (9.41)$$

- We have expressed the filtered noise $\mathbf{n(t)}$ at the band-pass filter output in Fig. 9.13 in terms of its in-phase and quadrature components

$$n(t) = n_I(t) \cos(2\pi f_c t) - n_Q(t) \sin(2\pi f_c t) \quad (9.42)$$

9.7: Detection of Frequency Modulation (FM)

POST-DETECTION SNR

- We may equivalently express $n(t)$ in terms of its envelope and phase as

$$n(t) = r(t) \cos[2\pi f_c t + \phi_n(t)] \quad (9.43)$$

- where the envelope is

$$r(t) = [n_I^2(t) + n_Q^2(t)]^{1/2} \quad (9.44)$$

- and the phase is

$$\phi_n(t) = \tan^{-1} \left(\frac{n_Q(t)}{n_I(t)} \right) \quad (9.45)$$

9.7: Detection of Frequency Modulation (FM)

POST-DETECTION SNR

- To proceed, we note that the phase of $s(t)$ is

$$\phi(t) = 2\pi k_f \int_0^t m(\tau) d\tau \quad (9.46)$$

- Combining Eqs. (9.40), (9.43), and (9.46), the noisy signal at the output of the band-pass filter may be expressed as

$$\begin{aligned} x(t) &= s(t) + n(t) \\ &= A_c \cos[2\pi f_c t + \phi(t)] + r(t) \cos[2\pi f_c t + \phi_n(t)] \end{aligned} \quad (9.47)$$



9.7: Detection of Frequency Modulation (FM)

POST-DETECTION SNR

- It is informative to represent by means of a phasor diagram, as in Fig. 9.15 where we have used the signal term as the reference

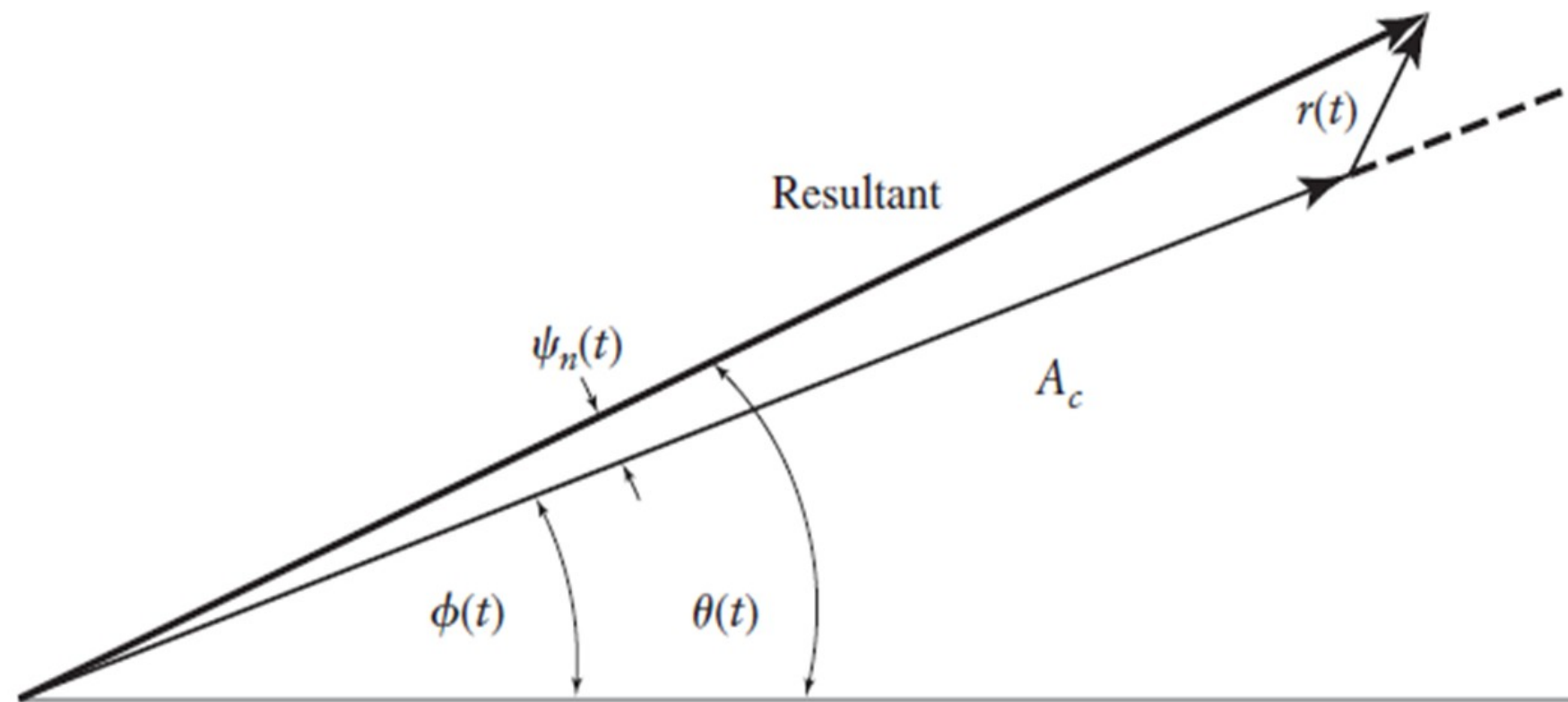


FIGURE 9.15 Phasor diagram for FM signal plus narrowband noise assuming high carrier-to-noise ratio.

$$x(t) = A_c \cos[2\pi f_c t + \phi(t)] + r(t) \cos[2\pi f_c t + \phi_n(t)]$$

9.7: Detection of Frequency Modulation (FM)

POST-DETECTION SNR

- In Fig. 9.15, the amplitude of the noise is $r(t)$ and the phase difference $\psi_n(t) = \phi_n(t) - \phi(t)$ is the angle between the noise phasor and the signal phasor.
- The phase $\theta(t)$ of the resultant is given by

$$\theta(t) = \phi(t) + \tan^{-1} \left\{ \frac{r(t) \sin(\psi_n(t))}{A_c + r(t) \cos(\psi_n(t))} \right\} \quad (9.48)$$

- The envelope of $x(t)$ is of no interest to us, because the envelope variations at the bandpass filter output *are removed by the limiter*

9.7: Detection of Frequency Modulation (FM)

POST-DETECTION SNR

- To obtain useful results, we make some approximations regarding $\theta(t)$:
- As $\tan(x) \approx x$, as $x \ll 1$, the expression for the phase simplifies to

$$\theta(t) = \phi(t) + \frac{r(t)}{A_c} \sin[\psi_n(t)] \quad (9.49)$$

9.7: Detection of Frequency Modulation (FM)

POST-DETECTION SNR

- We simplify this expression even further by ignoring the modulation component in the second term of Eq. (9.49), and *replacing $\psi_n(t) = \phi_n(t) - \phi(t)$ with $\phi_n(t)$* ,
- because $\phi_n(t)$ is uniformly distributed between 0 and 2π radians and, since $\phi_n(t)$ is independent of $\phi(t)$, it is reasonable to assume that the phase difference is also uniformly distributed over radians 2π .

9.7: Detection of Frequency Modulation (FM)

POST-DETECTION SNR

- Then noting that the quadrature component of the noise is $n_Q(t) = r(t) \sin[\phi_n(t)]$ we may simplify Eq. (9.49) to

$$\theta(t) = \phi(t) + \frac{n_Q(t)}{A_c} \quad (9.50)$$

- Using the expression for $\phi(t)$ given by Eq. (9.46), Eq. (9.50) can be expressed as

$$\theta(t) \approx 2\pi k_f \int_0^t m(\tau) d\tau + \frac{n_Q(t)}{A_c} \quad (9.51)$$

9.7: Detection of Frequency Modulation (FM)

POST-DETECTION SNR

- *Our objective is to determine the error in the instantaneous frequency of the carrier wave caused by the presence of the filtered noise $n(t)$*
- With an ideal discriminator, its output is proportional to the derivative $d\theta(t) / dt$
- Using the expression for $\theta(t)$ in Eq. (9.51), the ideal discriminator output, scaled by 2π is therefore

$$\begin{aligned} v(t) &= \frac{1}{2\pi} \frac{d\theta(t)}{dt} \\ &= k_f m(t) + n_d(t) \end{aligned} \quad (9.52)$$

9.7: Detection of Frequency Modulation (FM)

POST-DETECTION SNR

- where the noise term $n_d(t)$ is defined by

$$n_d(t) = \frac{1}{2\pi A_c} \frac{dn_Q(t)}{dt} \quad (9.53)$$

- We now see that, provided the carrier-to-noise ratio is high, the discriminator output $v(t)$ consists of the *original message signal $m(t)$* multiplied by the constant factor k_f plus an additive noise component $n_d(t)$

9.7: Detection of Frequency Modulation (FM)

The additive noise at the discriminator output is determined essentially by the quadrature component $n_Q(t)$ of the narrowband noise $n(t)$

- The *post-detection signal-to-noise ratio* is defined as the ratio of the average output signal power to the average output noise power

9.7: Detection of Frequency Modulation (FM)

- From Eq. (9.52) we see that the message component of the discriminator output, and therefore the low-pass filter output, is $k_f m(t)$
- Hence, the average output signal power is equal to $k_f^2 P$ where P is the average power of the message signal $m(t)$
- To determine the average output noise power, we note that the noise $n_d(t)$ at the discriminator output is proportional to the time derivative of the quadrature noise component $n_Q(t)$

9.7: Detection of Frequency Modulation (FM)

- Since the differentiation of a function with respect to time corresponds to multiplication of its Fourier transform by $-j2\pi f$, it follows that we may obtain the noise process by passing $n_Q(t)$ through a linear filter with a frequency response equal to

$$G(f) = \frac{j2\pi f}{2\pi A_c} = \frac{jf}{A_c} \quad (9.54)$$

9.7: Detection of Frequency Modulation (FM)

- This means that the power spectral density $S_{N_d}(f)$ of the noise $n_d(t)$ is related to the power spectral density $S_{N_Q}(f)$ of the quadrature noise component $n_Q(t)$ as follows:

$$\begin{aligned} S_{N_d}(f) &= |G(f)|^2 S_{N_Q}(f) \\ &= \frac{f^2}{A_c^2} S_{N_Q}(f) \end{aligned} \quad (9.55)$$

$$S_{N_d}(f) = \begin{cases} \frac{N_0 f^2}{A_c^2}, & |f| < \frac{B_T}{2} \\ 0, & \text{otherwise} \end{cases} \quad (9.56)$$

$$S_{N_o}(f) = \begin{cases} \frac{N_0 f^2}{A_c^2}, & |f| < W \\ 0, & \text{otherwise} \end{cases} \quad (9.57)$$

**For More
information
refer to
textbook**

9.7: Detection of Frequency Modulation (FM)

- *The average output noise power is determined by integrating the power spectral density $S_{N0}(f)$ from $-W$ to W .*
- Doing so, we obtain the following result:

$$\begin{aligned} \text{Average post-detection noise power} &= \frac{N_0}{A_c^2} \int_{-W}^W f^2 df \\ &= \frac{2N_0 W^3}{3A_c^2} \end{aligned} \quad (9.58)$$

9.7: Detection of Frequency Modulation (FM)

- Thereby,

$$\text{SNR}_{\text{post}}^{\text{FM}} = \frac{3A_c^2 k_f^2 P}{2N_0 W^3} \quad (9.59)$$

- Hence, the post-detection SNR of an FM demodulator has a nonlinear dependence on both *the frequency sensitivity* and *the message bandwidth*.

9.7: Detection of Frequency Modulation (FM)

Figure of Merit:

- With FM modulation, the modulated signal power is simply $A_c^2/2$, hence the reference SNR is $A_c^2/(2N_0W)$. Consequently, the figure of merit for this system is given by

$$\begin{aligned}
 \text{Figure of merit} &= \frac{\text{SNR}_{\text{post}}^{\text{FM}}}{\text{SNR}_{\text{ref}}} = \frac{\frac{3A_c^2 k_f^2 P}{2N_0 W^3}}{\frac{A_c^2}{2N_0 W}} \\
 &= 3 \left(\frac{k_f^2 P}{W^2} \right) \\
 &= 3D^2
 \end{aligned} \tag{9.60}$$

9.7: Detection of Frequency Modulation (FM)

$$\text{Figure of merit} = 3D^2$$

- Where, in the last line, we have introduced the definition $\mathbf{D} = \mathbf{k}_f \mathbf{P}^{1/2} / \mathbf{W}$ as modulation index and so $\mathbf{k}_f \mathbf{P}^{1/2}$ is *the deviation ratio* for the FM system in light of the material presented in Section 4.6.
- Recall from that section that the generalized Carson rule yields the transmission bandwidth for an FM signal

$$B_T = 2(k_f P^{1/2} + W) \approx 2k_f P^{1/2}$$

9.7: Detection of Frequency Modulation (FM)

- So, substituting $B_T/2$ for $k_f P^{1/2}$ in the definition of \mathbf{D} , the figure of merit for an FM system is approximately given by

$$\text{Figure of merit} \approx \frac{3}{4} \left(\frac{B_T}{W} \right)^2 \quad (9.61)$$

9.7: Detection of Frequency Modulation (FM)

$$\text{Figure of merit} \approx \frac{3}{4} \left(\frac{B_T}{W} \right)^2 \quad (9.61)$$

- Consequently, an increase in the transmission bandwidth provides a corresponding quadratic increase in the output signal-to-noise ratio with an FM system compared to the reference system
- Thus, when the carrier to noise level is high, unlike an amplitude modulation system an FM system allows us to trade bandwidth for improved performance in accordance with a square law.